

Based on Varadhan LD 2010.

0.1 LD Summary

A function $I(\cdot) : X \rightarrow [0, \infty]$ will be called a (proper) rate function, if it is lower semicontinuous and the level sets are compact in X .

Let P_n be a sequence of probability distributions on X . We say that P_n satisfies the large deviation principle on X with rate function I , if the following two statements hold. For every closed set $C \subset X$ and for every open $G \subset X$

$$\limsup n \rightarrow \infty \frac{1}{n} \log P_n(C) \leq - \inf_{x \in C} I(x), \quad (0.1.1)$$

$$\liminf n \rightarrow \infty \frac{1}{n} \log P_n(G) \geq - \inf_{x \in G} I(x). \quad (0.1.2)$$

Theorem Suppose P_n and Q_n are two sequences on two spaces X and Y satisfying the LDP with rate functions I and J , respectively. Then the sequence of product measures $R_n = P_n \times Q_n$ on $X \times Y$ satisfies an LDP with the rate function $K(x; y) = I(x) + J(y)$.

Theorem If P_n satisfies an LDP on X with a rate function I , and F is a continuous mapping from the Polish spaces¹ X to another Polish space Y , then the family $Q_n = P_n F^{-1}$ satisfies an LDP on Y with a rate function J given by

$$J(y) = \inf_{x: F(x)=y} I(x). \quad (0.1.3)$$

Theorem Assume that P_n satisfies an LDP with rate function I on X . Suppose that F is a bounded continuous function on X , and

$$a_n = \int_X dP_n(x) e^{nF(x)}. \quad (0.1.4)$$

Then

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log a_n = \sup_x [F(x) - I(x)]. \quad (0.1.5)$$

Theorem If P_n satisfies an LDP with rate function I and F is a bounded continuous function on X . Define

$$Q_n(A) = \frac{\int_A dP_n(x) e^{nF(x)}}{\int_X dP_n(x) e^{nF(x)}} \quad (0.1.6)$$

for Borel subset $A \subset X$. Then, Q_n satisfies an LDP on X as well with the new rate function

$$J(x) = I(x) - F(x) - \inf_{x \in X} [I(x) - F(x)]. \quad (0.1.7)$$

¹A Polish space is a separable completely metrizable topological space; that is, a space homeomorphic to a complete metric space that has a countable dense subset.

0.2 Sanov's theorem

Consider a sequence of i.i.d. random variables with values in some complete separable metric space X with a common distribution α . Then the sample distribution

$$\beta_n = \frac{1}{n} \sum_j \delta_{x_j} \quad (0.2.1)$$

generates a measure P_n on the space of measures $M(X)$ on X . LLN means P_n to converge d_α .

Theorem The sequence $\{P_n\}$ satisfies a large deviation principle on $M(X)$ with the rate function $I(\beta)$ given by

$$I(\beta) = \int \frac{d\beta}{d\alpha} \log \frac{d\beta}{d\alpha} d\alpha = \int \log \frac{d\beta}{d\alpha} d\beta, \quad (0.2.2)$$

If not $\beta \ll \alpha$ $I(\beta) = +\infty$

The proof uses the following lemma

Lemma Let α, β be two probability distributions on a measure space (X, \mathcal{B}) . Let $B(X)$ be the space of bounded measurable functions on (X, \mathcal{B}) . Then

$$I(\beta) = \sup_{f \in B(X)} \left[\int f(x) d\beta(x) - \log \int e^{f(x)} d\alpha(x) \right]. \quad (0.2.3)$$

Its demo uses

$$x \log x - x + 1 = \sup_y [xy - (e^y - 1)]. \quad (0.2.4)$$

Corollary Let $\{X_i\}$ be i.i.d.r.v with values in a separable Banach space X with a common distribution α . Assume

$$E \left[e^{\theta \|X\|} \right] < \infty \quad (0.2.5)$$

satisfies a large deviation principle with rate function

$$H(x) = \sup_{y \in X^*} \left[\langle y | x \rangle - \log \int e^{\langle y | x \rangle} d\alpha(x) \right]. \quad (0.2.6)$$

0.3 Scaled processes and escaping rate

Theorem [Schilder] Let us consider the family of stochastic process $\{x_\varepsilon(t)\}$ defined by

$$x_\varepsilon(t) = \sqrt{\varepsilon} B(t) \quad (0.3.1)$$

or equivalently

$$x_\varepsilon(t) = B(\varepsilon t) \quad (0.3.2)$$

for t in some fixed time interval, say $[0, 1]$ where B is the standard Brownian motion. The distributions of $x_\varepsilon(\cdot)$ induce a family of scaled Wiener processes on $C[0, 1]$ that we denote by Q_ε . In the $\varepsilon \rightarrow 0$ limit, the LDP of Q_ε is with the following rate function

$$I(f) = \frac{1}{2} \int_0^1 |f'(t)|^2 dt \quad (0.3.3)$$

if $f(0) = 0$ and f' is square integrable; otherwise, $I(f) = +\infty$.

Strassen's theorem about the iterated logarithm.

0.4 Markov process

Suppose X_1, \dots, X_n, \dots is a Markov Chain on a finite state space F . The Markov Chain will be assumed to have a stationary transition probability given by a stochastic matrix $\pi = \pi(x \rightarrow y)$. We will assume that all the entries of π are positive, imposing thereby a strong irreducibility condition on the Markov Chain. Under these conditions there is a unique invariant or stationary distribution $p(x)$ satisfying

$$p(x) = \sum_y p(y)\pi(y \rightarrow x). \quad (0.4.1)$$

Let us suppose that $V(x) : F \rightarrow \mathbb{R}$ is a function defined on the state space with a mean value of $m = \sum_x V(x)p(x)$ with respect to the invariant distribution. By the ergodic theorem, for any starting point x ,

$$\lim_{n \rightarrow \infty} P_x \left[\left| \frac{1}{n} \sum_j V(X_j) - m \right| \geq a \right] = 0, \quad (0.4.2)$$

where $a > 0$ is arbitrary and P_x denotes, as is customary, the measure corresponding to the Markov Chain initialized to start from the point $x \in F$.

For any V

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log E_x [\exp[V(x_1) + \dots + V(X_n)]] = \log \sigma(V) \quad (0.4.3)$$

exists, where $\sigma(V)$ is the PF eigenvalue of the matrix

$$\psi_V = \pi_V(x \rightarrow y) = \pi(x \rightarrow y)e^{V(x)}. \quad (0.4.4)$$

This follows from

$$E_x [\exp[V(x_1) + \dots + V(X_n)]] = \sum_y (\pi_V)^n(x \rightarrow y). \quad (0.4.5)$$

Theorem For any Markov Chain with a transition probability matrix π with positive entries, the probability distribution of $(1/n) \sum_{j=1}^n V(X_j)$ satisfies an LDP with a rate function

$$h(a) = \sup_\lambda [\lambda a - \log \sigma(\lambda V)]. \quad (0.4.6)$$

There is an interesting way of looking at $\sigma(V)$. If $V(x) = \log(u(x)/(\pi u(x)))$, then $f(x) = (\pi u)(x)$ is a column eigenfunction for π_V with eigenvalue $\sigma = 1$. Therefore

$$\log \sigma(\log(u/\pi u)) = 0. \quad (0.4.7)$$

0.5 Applications

For a Markov chain on a

finite state space X , having $\pi(x \rightarrow y)$ as the probability of transition from the state x to the state y . The following limit

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log E_x[\exp[V(x_1) + \cdots + V(X_n)]] = \lambda(V) \quad (0.5.1)$$

exists and is independent of x :

$$\lambda(V) = \sup_{q \in \mathcal{P}} \left[\sum_x V(x)q(x) - I(q) \right], \quad (0.5.2)$$

where $q = \{q(x)\}$ is a probability distribution on X , \mathcal{P} is the space of such probability distributions and $I(q)$ is the large deviation rate function for the distribution Q_n on \mathcal{P} , of the empirical distribution

$$p_n(x) = \frac{1}{n} \sum_{i=1}^n \chi_x(X_i). \quad (0.5.3)$$

This can be generalized to

$$\lambda_2(V) = \lim_{n \rightarrow \infty} \frac{1}{n} \log E_x[\exp[V(x_1, X_2) + V(X_2, X_3) + \cdots + V(X_n, X_{n+1})]]. \quad (0.5.4)$$

Collection of non-interacting Brownian particles

We have $N = \bar{\rho}L^3$ particles in a L^3 -cube. If the initial configuration with an empirical density

$$\nu_0(dx) = \frac{1}{L^3} \sum_{i=1}^N \delta(x_i - x) \quad (0.5.5)$$

has a deterministic limit $\rho_0(x)dx$, then the empirical distribution

$$\nu_t(dx) = \frac{1}{L^3} \sum_{i=1}^N \delta(x_i(t) - x) \quad (0.5.6)$$

has a deterministic limit $\rho(t, x)dx$ as $t \rightarrow \infty$ and $\rho(t, x)$ can be obtained from $\rho_0(x)$ by solving the heat equation

$$\frac{\partial \rho}{\partial t} = \frac{1}{2} \Delta \rho \quad (0.5.7)$$

with the initial condition $(\rho(0, x) = \rho_0(x))$.

The proof is an elementary law of large numbers argument involving a calculation of two moments. Let $f(x)$ be a continuous function on T^3 (3-torus) and let us calculate for

$$U = \frac{1}{L^3} \sum_i f(x_i(t)) \quad (0.5.8)$$

the first two moments given the initial configuration (x_1, \dots, x_N)

$$E(U) = \frac{1}{L^3} \sum_i \int_{T^3} dy f(y) \rho(t, y) \quad (0.5.9)$$

and an elementary calculation reveals that the conditional expectation converges to the following constant.

$$\int_{T^3} \int_{T^3} f(y) p(t, x, y) \rho_0(x) dy dx = \int_{T^3} f(y) \rho(t, y) dy \quad (0.5.10)$$

The independence clearly provides a uniform upper bound of order L^3 for the conditional variance that clearly goes to 0. Of course on T^3 we could have had a process obtained by rescaling a random walk on a large torus of size L . Then the hydrodynamic scaling limit would be a consequence of central limit theorem for the scaling limit of a single particle and the law of large numbers resulting from the averaging over a large number of independently moving particles.

Simple exclusion process

The particles move randomly. Each particle waits for an exponential random time and then tries to jump from the current site x to a new site y . The new site y is picked randomly according to a probability distribution $\pi(x \rightarrow y)$. In particular, $\sum_y \pi(x \rightarrow y) = 1$ for every x . A jump is possible only when the destination is empty.

0.6 LD Introduction, Varadhan 2012

$$dx_\varepsilon(t) = b(x_\varepsilon(t))dt + \sqrt{\varepsilon}dB. \quad (0.6.1)$$

Theorem [Schilder] For $b = 0$ let the path measure for x_ε be Q_ε . Then, asymptotically in $\varepsilon \rightarrow 0$

$$\varepsilon \log Q_\varepsilon[C] \simeq - \inf_{g \in C} \frac{1}{2} \int ds g'(s)^2, \quad (0.6.2)$$

where C is a set of 'good functions.'

[Demo] Kac path

$$Q_\varepsilon[dx] = \mathcal{D}[x] \exp \left\{ -\frac{1}{2\varepsilon} \int ds \dot{x}^2 \right\} \quad (0.6.3)$$

Formally, we need

$$\int_C \mathcal{D}[x] \exp \left\{ -\frac{1}{2\varepsilon} \int ds \dot{x}^2 \right\} \quad (0.6.4)$$

Therefore, the variational principle follows.

For (0.5.11)

$$Q_\varepsilon[dx] = \mathcal{D}[x] \exp \left\{ -\frac{1}{2\varepsilon} \int ds [\dot{x} - b(x)]^2 \right\} \quad (0.6.5)$$

Therefore,

Theorem [Schilder] For (0.5.11) let the path measure for x_ε be P_ε . Then, asymptotically in $\varepsilon \rightarrow 0$

$$\varepsilon \log P_\varepsilon[C] \simeq - \inf_{f \in C} \frac{1}{2} \int ds [f'(s) - b(f(s))]^2, \quad (0.6.6)$$

where C is a set of ‘good functions.’

Escape:

Consider

$$dx = -\nabla V dt + \sqrt{\varepsilon} dB. \quad (0.6.7)$$

We know

$$\varepsilon \log P_\varepsilon[C] \simeq - \inf_{f \in C} \frac{1}{2} \int_0^T ds [f'(s) + \nabla V(f(s))]^2, \quad (0.6.8)$$

If C is a set of function with $f(0) = x_0$ and $f(T) = x$, then

$$\inf_{T \in [0, \infty]} \inf_{f \in C} \frac{1}{2} \int_0^T ds [f'(s) + \nabla V(f(s))]^2 = 2[V(x) - V(x_0)]. \quad (0.6.9)$$

This tells that the escape is from min of $V(x)$ at the boundary.

0.7 Long time, Varadhan 2012

Consider Markov $p(x \rightarrow y)$ with equilibrium π : $\sum_y \pi(y) P(y \rightarrow x) = \pi(x)$. The ergodic theorem tells us

$$\frac{1}{n} \sum_{j=1}^n f(X_j) \rightarrow \sum_x f(x) \pi(x). \quad (0.7.1)$$

Let the empirical distribution be

$$\mu_{n,x} = \frac{1}{n} \sum_{j=1}^n \delta_{X_j} \quad (0.7.2)$$

where x is the starting point.

$$Q_{n,x}(C) = P_x \left[\frac{1}{n} \sum_{j=1}^n \delta_{X_j} \in C \right], \quad (0.7.3)$$

where C is a set of measures. LLN tells us $Q_{n,x} \rightarrow \delta_\pi$ ($\mu \rightarrow \pi$). LDP for the empirical measure reads

$$P[\mu_{n,x} \sim \mu] \sim e^{-nI(\mu)}. \quad (0.7.4)$$

As to the expectation value

$$P\left[\frac{1}{n} \sum_{i=1}^n f(X_i) \sim q\right] \sim e^{-nJ(q)}, \quad (0.7.5)$$

where

$$J(q) = \inf_{\mu: \sum_x \mu(x)f(x)=q} I(\mu). \quad (0.7.6)$$

We can obtain

$$P[X_i \in A \text{ for } 1 \leq i \leq n] \sim - \inf_{\mu: \mu(A)=1} I(\mu). \quad (0.7.7)$$

Formally, we are interested in $\prod_i \chi_A(X_i) = 1$. That is,

$$-\frac{1}{n} \sum_{i=1}^n \log \chi_A(X_i) < +\infty \quad (0.7.8)$$

Looking at (0.5.25), set $f = -\log \chi_A$. $\sum_x \chi_A(x)\mu(x) < +\infty$ implies $\mu(A) = 1$.

Let us introduce a partition function

$$Z_P(V) = E_P \left[\exp \left\{ \sum_{j=1}^n V(X_j) \right\} \right] \sim e^{nA(V)} \quad (0.7.9)$$

Here,

$$\exp \left\{ \sum_{j=1}^n V(X_j) \right\} = \exp \left\{ n \int \mu_{n,x}(dx) V(x) \right\} \quad (0.7.10)$$

Therefore, (\mathcal{D} always denotes ‘uniform measure’)

$$E_P \left[\exp \left\{ \sum_{j=1}^n V(X_j) \right\} \right] = \int \mathcal{D}[\mu] \exp \left\{ n \int \mu(dx) V(x) \right\} e^{-nI(\mu)} \quad (0.7.11)$$

Thus, we get

$$\frac{1}{n} \log Z_P(V) \rightarrow A(V) = \sup_{\mu} \left[\int \mu(dx) V(x) - I(\mu) \right] \quad (0.7.12)$$

Therefore,

$$I(\mu) = \sup_V \left[\int \mu(dx) V(x) - A(V) \right]. \quad (0.7.13)$$

Notice that $A(V+c) = A(V) + c$ for any constant c . Thus, to compute (0.5.32) we may impose the condition that $A(V) = 0$.

Theorem 3.1.3. Let $p(x, y) > 0$ be the transition probability of a Markov chain $\{X_i\}$ on a finite state space X . Then, the measure on the set of all the sampled measures $Q_{n,x}$ satisfies a large deviation principle with rate function

$$I(\mu) = \sup_u \sum_x \mu x \log \frac{u(x)}{(\pi u)(x)} = \inf_{\nu: \mu q = u} \sum_{x,y} \mu(x) q(x, y) \log \frac{q(x, y)}{\pi(x, y)}. \quad (0.7.14)$$

Let us try a different demonstration, following YO 1989

Here, a probability space $\{P, \mathcal{B}, \Omega\}$ is fixed.

Level 1:

$$Q_N^{(1)}(B) = P \left[\omega \left| e_N(X) = \frac{1}{N} \sum_{j=1}^N X_j(\omega) \in B \right. \right] \quad (0.7.15)$$

Consider the following 'partition function':

$$Z_N^{(1)}(t) = E_P \left[\exp \left\{ t \sum_{j=1}^N X_j(\omega) \right\} \right] = \int Q_N^{(1)}(dy) e^{tNy}. \quad (0.7.16)$$

(Negative) free energy

$$a^{(1)}(t) = \lim_{N \rightarrow \infty} \frac{1}{N} \log Z_N^{(1)}(t) = \sup_y [ty - I^{(1)}(y)] \quad (0.7.17)$$

Level 2

$$Q_N^{(2)}(B) = P \left[\omega \left| \mu_N = \frac{1}{N} \sum_{j=1}^N \delta_{X_j(\omega)} \in B \right. \right] \quad (0.7.18)$$

Consider the following 'partition function':

$$Z_N^{(2)}(\phi) = E_P \left[\exp \left\{ \sum_{j=1}^N \phi(X_j(\omega)) \right\} \right] = \int Q_N^{(2)}(d\mu) e^{N \int \phi(y) \mu(dy)}. \quad (0.7.19)$$

(Negative) free energy

$$a^{(2)}(\phi) = \lim_{N \rightarrow \infty} \frac{1}{N} \log Z_N^{(2)}(\phi) = \sup_{\mu} \left[\int \phi(x) \mu(dx) - I^{(2)}(\mu) \right] \quad (0.7.20)$$

A variational calculation gives

$$I^{(2)}(\mu) = \int d\mu \log \frac{d\mu}{dm}. \quad (0.7.21)$$

It is basically the KS entropy.

Notice that this is for iid

$$\begin{aligned} & \frac{d}{d\phi(x)} \frac{1}{N} \log E_P \left[\exp \left\{ \sum_{j=1}^N \phi(X_j(\omega)) \right\} \right] = \frac{d}{d\phi(x)} \frac{1}{N} \log \int dm(\omega) \exp \left\{ \sum_{j=1}^N \phi(X_j(\omega)) \right\} \\ &= \frac{1}{N} \frac{\int dm(\omega) \sum_j \delta(x - X_j(\omega)) \exp \left\{ \sum_{j=1}^N \phi(X_j(\omega)) \right\}}{\int dm(\omega) \exp \left\{ \sum_{j=1}^N \phi(X_j(\omega)) \right\}} = \frac{m(\delta_x) \exp[\phi(x)]}{\int dm(\omega) \exp[\phi(X_1(\omega))]} \end{aligned} \quad (0.7.22)$$

Thus, an explicit calculation of

$$I^{(2)}(\mu) = \sup_{\phi} \left[\int \phi(x) \mu(dx) - a^{(2)}(\phi) \right] \quad (0.7.23)$$

gives

$$\mu(\delta_x) = \frac{m(\delta_x) \exp[\phi(x)]}{\int dm(\omega) \exp[\phi(X_1(\omega))]} \quad (0.7.24)$$

That is,

$$\frac{d\mu}{dm} \int dm(\omega) \exp[\phi(X_1(\omega))] = \exp[\phi(x)] \quad (0.7.25)$$

or

$$\phi(x) = \log \frac{d\mu}{dm} + \log \int dm(\omega) \exp[\phi(X_1(\omega))]. \quad (0.7.26)$$

That is

$$\int \phi d\mu = \int d\mu \log \frac{d\mu}{dm} + \log \int dm(\omega) \exp[\phi(X_1(\omega))], \quad (0.7.27)$$

but the last term is $a^{(2)}(\phi)$: we get a Fenchel's equality

$$\int d\mu \log \frac{d\mu}{dm} = \int \phi d\mu - a^{(2)}(\phi) = I^{(2)}(\mu). \quad (0.7.28)$$

Level 2 to Level 1

The contraction principle tells us

$$I^{(1)}(x) = \inf_{\mu | \int y \mu(dy) = x} I^{(2)}(\mu), \quad (0.7.29)$$

so using Lagrange's multiplier, we can write

$$I^{(1)}(x) = \inf_{\mu, t} \left[I^{(2)}(\mu) - t \left(\int y \mu(dy) - x \right) \right] = - \sup_{\mu, t} \left[t \left(\int y \mu(dy) - x \right) - I^{(2)}(\mu) \right] \quad (0.7.30)$$

That is,

$$I^{(1)}(x) = - \sup_t a^{(2)}(t(y - x)), \quad (0.7.31)$$

where y denotes the variable of the function $\phi(y) = y - x$.

True time LD requires some trick as is formally followed in YO PTP, we could use level 2 for samples.

Let us consider the following partition function (σ is the shift)

$$Q_N^{(2)}(B) = P \left[\omega \left| \frac{1}{N} \sum_{j=1}^N \left[\sum_{i=1}^T \delta_{\sigma^i \omega_j} \right] \in B \right] \simeq e^{-NI^{(2)}(\mu_T)} \quad (0.7.32)$$

$$Z_{N,T}^{(2)}(\phi) = E_P \left[\exp \left\{ \sum_N \left[\sum_{j=1}^T \phi(\sigma^j \omega_N) \right] \right\} \right] = \int Q_N^{(2)}(d\mu_T) \exp \left\{ N \int \left[\sum_{j=1}^T \phi(\sigma^j \omega) \right] \mu_T(\omega) \right\}. \quad (0.7.33)$$

Define

$$a_T^{(2)}(\phi) = \frac{1}{N} \log Z_{N,T}^{(2)}(\phi) \quad (0.7.34)$$

From (0.5.52)

$$a_T^{(2)}(\phi) = \sup_{\mu_T} \left[\int \sum_{j=1}^T \phi(\sigma^j \omega) \mu_T(d\omega) - I_T^{(2)}(\mu_T) \right] \quad (0.7.35)$$

Note that, actually, $\sum_{j=1}^T \phi(\sigma^j \omega)$ can be replaced by a general function $\phi(\omega, \sigma\omega, \dots, \sigma^T \omega)$. From the above calculation

$$I^{(2)}(\mu) = \int d\mu \log \frac{d\mu}{dm} \quad (0.7.36)$$

Here, μ and m are measures on the path space. We can write

$$I_T^{(2)}(\mu_T) = \sup_{\mu_T} \left[\int \sum_{j=1}^T \phi(\sigma^j \omega) \mu_T(d\omega) - a_T^{(2)}(\phi) \right] \quad (0.7.37)$$

Differentiating (0.5.54) wrt $\phi(\omega)$ we get

$$\frac{\delta a_T^{(2)}(\phi)}{\delta \phi(\omega)} = \frac{1}{N} \sum_N \frac{\int dm(\omega_N) \left[\sum_{j=1}^T \delta(\sigma^j \omega_N - \omega) \right] \exp \left\{ \sum_N \left[\sum_{j=1}^T \phi(\sigma^j \omega_N) \right] \right\}}{\int dm(\omega_N) \exp \left\{ \sum_N \left[\sum_{j=1}^T \phi(\sigma^j \omega_N) \right] \right\}} \quad (0.7.38)$$

$$= \frac{\int dm(\omega') \left[\sum_{j=1}^T \delta(\sigma^j \omega' - \omega) \right] \exp \left[\sum_{j=1}^T \phi(\sigma^j \omega') \right]}{\int dm(\omega') \exp \left[\sum_{j=1}^T \phi(\sigma^j \omega') \right]} \quad (0.7.39)$$

$$= \sum_{j=1}^T \frac{m(\delta_\omega) \exp \left[\phi(\sigma^{1-j} \omega) + \dots + \phi(\omega) + \dots + \phi(\sigma^{T-j} \omega) \right]}{\int dm(\omega') \exp \left[\sum_{j=1}^T \phi(\sigma^j \omega') \right]} \quad (0.7.40)$$

$$(0.7.41)$$

If we may use the stationarity of m , we get

$$\frac{\delta a_T^{(2)}(\phi)}{\delta \phi(\omega)} = T \frac{m(\delta_\omega) \exp \left[\sum_{j=1}^T \phi(\sigma^j \omega) \right]}{\int dm(\omega') \exp \left[\sum_{j=1}^T \phi(\sigma^j \omega') \right]} \quad (0.7.42)$$

Differentiating (0.5.56) wrt $\phi(\omega)$ we get

$$\int \sum_{j=1}^T \delta(\sigma^j \omega - \omega) \mu_T(d\omega) - T \frac{m(\delta_\omega) \exp \left[\sum_{j=1}^T \phi(\sigma^j \omega) \right]}{\int dm(\omega') \exp \left[\sum_{j=1}^T \phi(\sigma^j \omega') \right]} = 0 \quad (0.7.43)$$

This may be rewritten as

$$T \mu_T(\delta_\omega) - T \frac{m(\delta_\omega) \exp \left[\sum_{j=1}^T \phi(\sigma^j \omega) \right]}{\int dm(\omega') \exp \left[\sum_{j=1}^T \phi(\sigma^j \omega') \right]} = 0 \quad (0.7.44)$$

This is an equation similar to the one in YO.

Donsker-Varadhan: Asymptotic Evaluation of Certain Markov Process Expectations for Large Time, I
CPAM 28 1 (1975).

Let u be a function on the state space.

$$\pi u(x) = \int u(y) \pi(x, dy). \quad (0.7.45)$$

Here, $\pi(x, dy)$ is the transition probability from x into dy . Let L_n be the empirical distribution, and P_x be the stationary measure.

$$Q_{n,x}(B) = P_x(L_n \in B) \quad (0.7.46)$$

Then

Theorem 1. For any closed set C (a set of probability measures)

$$\lim_{N \rightarrow \infty} \frac{1}{N} \log Q_{N,x}(C) \simeq \inf_{\mu \in C} I(\mu) \quad (0.7.47)$$

with (Markov version of Sanov's theorem)

$$I(\mu) = - \inf_u \int \mu(dx) \log \left(\frac{\pi u}{u} \right). \quad (0.7.48)$$

Let $V = \pi u$ and $e^{-W} = u/V$. Averaging $\langle \cdot \rangle_x$ over all the processes starting from x

$$\langle \exp\{-[W(X_0) + W(X_1) + \cdots + W(X_{N-1})]\} V(X_{N-1}) \rangle_x = \left\langle \frac{u(X_0)u(X_1) \cdots u(X_{N-1})}{V(X_0)V(X_1) \cdots V(X_{N-1})} V(X_{N-1}) \right\rangle_x \quad (0.7.49)$$

$$= \left\langle \frac{u(X_0)u(X_1) \cdots u(X_{N-2})}{V(X_0)V(X_1) \cdots V(X_{N-2})} u(X_{N-1}) \right\rangle_x \quad (0.7.50)$$

Notice that the Markov property implies that

$$P(X_{N-1}, X_{N-2}, \dots, X_2, X_1 | X_0 = x) dX_{N-1} \cdots dX_1 = \pi(x, dX_1) \pi(X_1, dX_2) \cdots \pi(X_{N-2}, dX_{N-1}) \quad (0.7.51)$$

Thus, the above average reads

$$= \int \cdots \int \frac{u(X_0)u(X_1) \cdots u(X_{N-2})}{V(X_0)V(X_1) \cdots V(X_{N-2})} u(X_{N-1}) \pi(x, dX_1) \pi(X_1, dX_2) \cdots \pi(X_{N-2}, dX_{N-1}) \quad (0.7.52)$$

$$= \int \cdots \int \frac{u(X_0)u(X_1) \cdots u(X_{N-2})}{V(X_0)V(X_1) \cdots V(X_{N-2})} V(X_{N-2}) \pi(x, dX_1) \pi(X_1, dX_2) \cdots \pi(X_{N-2}, dX_{N-2}) \quad (0.7.53)$$

$$= \int \cdots \int \frac{u(X_0)u(X_1) \cdots u(X_{N-3})}{V(X_0)V(X_1) \cdots V(X_{N-3})} u(X_{N-2}) \pi(x, dX_1) \pi(X_1, dX_2) \cdots \pi(X_{N-3}, dX_{N-2}) \quad (0.7.54)$$

...

$$= u(x). \quad (0.7.55)$$

Thus, we conclude

$$\langle \exp\{-[W(X_0) + W(X_1) + \cdots + W(X_{N-1})]\} V(X_{N-1}) \rangle_x = u(x). \quad (0.7.56)$$

Here u is bounded and V is bounded from below (ergodicity assumed), so (0.5.75) implies

$$\langle \exp\{-[W(X_0) + W(X_1) + \cdots + W(X_{N-1})]\} \rangle_x \leq u(x) / \inf V(x) \leq M \quad (0.7.57)$$

for some positive constant H . That this is independent of N is the key observation.

On the other hand

$$\exp\{-[W(X_0) + W(X_1) + \cdots + W(X_{N-1})]\} = \exp\{-N[[W(X_0) + W(X_1) + \cdots + W(X_{N-1})]/N]\} \quad (0.7.58)$$

$$= \exp[-N \int W(y) L_N(dy)] \quad (0.7.59)$$

where L_N is the empirical measure. Therefore,

$$\langle \exp\{-[W(X_0) + W(X_1) + \cdots + W(X_{N-1})]\} \rangle_x = \left\langle \exp[-N \int W(y) L_N(dy)] \right\rangle_x \leq M \quad (0.7.60)$$

Inn (0.5.79) the average is over (empirical) measures Q_x starting from x . Therefore, for any set of measures C

$$\langle \exp\{-[W(X_0) + W(X_1) + \cdots + W(X_{N-1})]\} \rangle_x \geq Q_x(C) \exp[-N \sup_{\ell \in C} \int W(y) \ell(dy)] \quad (0.7.61)$$

With (0.5.79)

$$M \geq Q_x(C) \exp[-N \sup_{\ell \in C} \int W(y) \ell(dy)] \quad (0.7.62)$$

or

$$Q_x(C) \leq M \exp[N \sup_{\ell \in C} \int W(y) \ell(dy)] \quad (0.7.63)$$

Thus,

$$\limsup_{N \rightarrow \infty} \frac{1}{N} \log Q_x(C) \leq \sup_{\ell \in C} \int W(y) \ell(dy) = \sup_{\ell \in C} \int \log \left(\frac{\pi u}{u} \right) (y) \ell(dy) \quad (0.7.64)$$

with an arbitrary u , so we may choose inf wrt u .

Informally, (0.5.79)

$$\left\langle \exp[-N \int W(y) L_N(dy)] \right\rangle_x = \int_{\nu} \exp[-N \int W(y) \nu(dy)] P(L_N \sim \delta \nu) \quad (0.7.65)$$

$$= \int_{\nu} \exp[-N \int W(y) \nu(dy)] e^{-NI(\nu)} \leq M, \quad (0.7.66)$$

where M is not N -dependent. This implies

$$\inf_u \int \log \left(\frac{\pi u}{u} \right) (y) \nu(dy) + I(\nu) = 0. \quad (0.7.67)$$

In case the time is continuous: Notice that

$$\pi(x, dy) = G(y, x, t = 1) dy \quad (0.7.68)$$

where G is the Green's function for the time evolution operator

$$\frac{\partial}{\partial t} G(y, x, t) = LG(y, x, t) + \delta(t) \delta(y - x). \quad (0.7.69)$$

For the Brownian motion $L = (1/2)\Delta$. Therefore,

$$\lim_{t \rightarrow 0} \frac{1}{t} \log \left(\frac{e^{tL} u}{u} \right) = \frac{Lu}{u} \quad (0.7.70)$$

Thus

$$I(\nu) = - \inf_u \int \frac{Lu}{u}(y) \nu(dy). \quad (0.7.71)$$

For the Wiener process $L = (1/2)\Delta$, so

$$I(\nu) = - \inf_u \int \frac{\Delta u}{2u}(y) \nu(dy). \quad (0.7.72)$$

Let f be the Radon-Nikodym derivative $f = \nu(dy)/dy$. Then,

$$\frac{\delta}{\delta u} \int \frac{\Delta u}{2u}(y) f dy = - \frac{\Delta u}{2u^2} f + \Delta \frac{f}{2u} = 0 \quad (0.7.73)$$

. Let us introduce $B = f/2u^2$. The above formula reads

$$-B\Delta u + \Delta(uB) = 2 \text{grad } u \cdot \text{grad } B + u\Delta B = 0 \quad (0.7.74)$$

Let us multiply u and we get

$$\text{grad}u^2 \cdot \text{grad}B + u^2 \Delta B = \text{div}(u^2 \text{grad}B) = 0 \quad (0.7.75)$$

Thus, $u^2 \text{grad}B = 0$ (assuming the constant vanished far away). This reads

$$\frac{1}{2} \text{grad}f + \frac{f}{4u} \text{grad}u = 0 \Rightarrow \frac{\text{grad}u}{u} = -\frac{\text{grad}f}{2f} \quad (0.7.76)$$

On the other hand

$$I(\nu) = -\inf_u \int \text{grad}u \cdot \text{grad}\left(\frac{f}{2u}\right) dy = -\inf_u \int \left(\frac{\text{grad}u}{2u} \cdot \text{grad}f - \frac{(\text{grad}u)^2}{2u^2} f\right) dy \quad (0.7.77)$$

$$= + \int \frac{(\text{grad}f)^2}{8f} dy = -\frac{1}{2} \int \sqrt{f} \Delta \sqrt{f} dy \quad (0.7.78)$$

0.8 Hydrodynamic Scaling, Varadhan 2012

The dynamical system has five conserved quantities. The total number N of particles, the total momenta and the total energy. The hydrodynamic scaling in this context consists of rescaling space and time by a factor of ℓ . The rescaled space is the 3-unit torus T^3 . The macroscopic quantities to be studied correspond to conserved quantities. For the number density

$$\int_{T^3} J(x) \rho_\ell(t, x) dx = \frac{1}{\ell^3} \sum_{i=1}^N J\left(\frac{\mathbf{r}_i(\ell t)}{\ell}\right). \quad (0.8.1)$$